Parallel Prediction of Stock Volatility

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ABSTRACT

Volatility is a measurement of the risk of financial products. A stock will hit new highs and lows over time and if these highs and lows fluctuate wildly, then it is considered a high volatile stock. Such a stock is considered riskier than a stock whose volatility is low. Although highly volatile stocks are riskier, the returns that they generate for investors can be quite high. Of course, with a riskier stock also comes the chance of losing money and yielding negative returns. In this project, we will use historic stock data to help us forecast volatility. Since the financial industry usually uses S&P 500 as the indicator of the market, we will use S&P 500 as a benchmark to compute the risk. We will also use artificial neural networks as a tool to predict volatilities for a specific time frame that will be set when we configure this neural network. There have been reports that neural networks with different numbers of layers and different numbers of hidden nodes may generate varying results. In fact, we may be able to find the best configuration of a neural network to compute volatilities. We will implement this system using the parallel approach. The system can be used as a tool for investors to allocating and hedging assets.

Keywords: Artificial Neural Network, Volatility, Parallel Processing

1. INTRODUCTION

The financial industry is an industry that requires multidisciplinary expertise. In order to be a good financial engineer, one should possess knowledge and skills in various areas, such as math, finance, economics, and computer science. In addition, one will also utilize analytical skills and logical reasoning in order to find meaning in the data collected and to make conclusions. For this project, we combine our skills in programming and our knowledge of finance in order to try to predict stock volatility. We will analyze whether the results are accurate, and if our method of getting to such a conclusion was effective and efficient.

The stock market can be very volatile and is sensitive to various factors and situations. For example, in cases where natural disasters, political turmoil, or economic and financial crises occur, financial assets tend to fluctuate very much.

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volatile stock. Such a stock is considered riskier than a stock whose volatility is low. High tech stocks usually have high volatility and is said to have a higher beta value, i.e., a beta value greater than 1. Although these stocks are riskier, the returns that they generate for investors, if positive, can be very high. On the other hand, a riskier stock means there's a greater chance of vielding negative returns and losing money. Unlike high tech stocks, stocks like utilities are more stable in their stock prices, so they are considered to have low volatility, which means having a beta value that is less than 1. A beta value of 0 signifies a security that has no volatility; for example, cash has beta value of 0. It is known that standard deviation alone cannot be used to measure volatility because, as illustrated by the history of the stock market, the market is not normally distributed and in reality, is skewed. Thus, historic stock data may in fact help us to measure volatility. In this paper, we will use historic data to help us to compute the volatility. We will use artificial neural networks as a tool to predict volatilities for a specific time frame that will be set when we configure this neural network. As a side note, there have been reports that neural networks with different layers and different nodes may generate varying results. In fact, we will vary the number of nodes to find the best configuration of the neural network, if one such configuration exists, for computing volatilities. We will implement this system using a parallel approach. The system can be used as a tool for investors to allocating and hedging assets.

Neural networks are popular in financial and economic computations. For example, Li and Liu used the LM BP algorithm to predict the Shanghai stock market [3]. Wang developed an HLP method that is able to get stock high/low points with differing frequency and amplitude. The extracted data are then fed into a neural network to forecast the stock direction and price [8]. Tirados and Jenq used neural networks to predict GDP with ten leading economic indicators as the input [7]. Lin and Feng combined neural networks and pattern matching techniques to analyze and to forecast oil stock price [4]. Zhou and Zhang used financial indicators such as moving averages, volumes, relative strength index, etc. on neural networks to predict future stock prices [9].

Additionally, Amornwattana et. al[1] proposed a hybrid artificial neural network (ANN) model for forecasting volatility to do options trading. Hajizadeh et al. [2] proposed a hybrid model with ANN to forecast the volatility of the S&P 500 index. Monfared and Enke [5][6] also proposed a hybrid GJR-GARCH Neural Network model to enhance the performance of volatility forecasting using an adaptive neural network filter for cancelling noise in the data. Youngmin Kima and David Enke discussed

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using neural networks to forecast volatility for an asset allocation strategy based on the target volatility [10]. Kim et. al[11] proposed a system for early warning of economic crisis.

In this project, we would like to find the local minimum number of hidden nodes in a single hidden layer that would be able to achieve the best prediction in terms of accuracy. We will use only a single hidden layer in our neural network, as illustrated in Figure 1 below, because adding more layers becomes computationally expensive very quickly while only a relatively small amount of performance improvements would be seen.

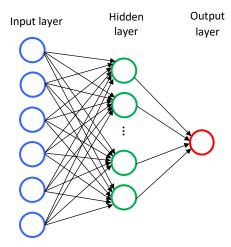


Figure 1. Diagram of the ANN

This proposed problem can benefit greatly from parallelism because most people usually try to find the number of hidden nodes to use through either trial-and-error or by simply using the same number of nodes in input layer. Both of these methods can be very ineffective. Using parallelism, we are able to speed up the process of finding a local optimal number of hidden nodes for fairly accurate stock price predictions, as seen later in the results. Predicting stock price, in turn, helps show stock volatility, as the difference between the actual price and predicted price will give insight into how volatile the stock is. This paper is organized in the following way: in the next section, we define some terms that we used in our project. Section 3 will describe the development of the system. We discuss the implementation results in section 4. Section 5 gives the conclusions.

2. TERMINOLGIES

Below are various terms we will use, as well as their meaning and significance within the scope of this paper.

MSE (mean squared error): This value is one of the criteria to stop the training of the neural network. MSE is defined as the sum of the square of errors of outputs divided by the total number of cases involved in the training. The error used here is defined as the difference between the actual (target) value and the predicted value generated from the artificial neural network (ANN). Note that there are other methods to compute the MSE, such as using validation data set to stop the training by checking if total number of accuracy is improved and if total accuracy hasn't, then one can stop the training. We did not use this method to stop the training in this project. To stop training, we set a

tolerable error and a maximum cycle, and the one that was reached first would stop the training.

Accuracy: Because the predicted price and the actual price must change in the same direction to be considered a good prediction for the stock market (and can at least help us to make the decision to either buy, sell or hold), accuracy can be defined as the number of same directional changes of predictions divided by total number of testing cases. We called this the "hit ratio." Another way to define it is to say that a lower MSE means a higher accuracy because it shows how close the predicted value is from the target value for the values that change in the same direction.

Speedup: This is defined as the ratio of sequential runtime divided by the parallel run time

Efficiency: This is defined as the speed up factor divided by the number of threads used to execute the program.

3. SYSTEM DESIGN AND IMPLEMENTATION

We implement the system using C/C++. There are 16 threads in the system that we used. The program can run multiple threads simultaneously. OpenMP is used to parallelize the program code. Since we'd like to find the local optimal hidden layer nodes, we structure our program so that we can use all threads as much as possible.

The pseudo code of our program is outlined below.

- Process command line arguments and set corresponding variables of the program
- Read in data file and put the data cases into data array for future reference.
- Process the data by normalization so the data values will be converted from arbitrary values to values between -1 and +1
- Initialize ANNs // the number of ANNs to be trained and tested
- 5. Parallel do the following using ANN with different hidden layer configuration {
- 6. While (MSE > tolerable error && cycle < maximum cycle) {
- 7. For all training data do {
 8. Forward-propagation
 9. Rackward propagation
- 9. Backward propagation of errors10. Update weights
- 11. }
 12. Compute MSE
- 12. Compute MSE 13.
- 14. // test this ANN
- 15. Test run current ANN with test data
- 16. Compute accuracy
- 17.

The first approach was to parallelize the execution of training of all configured ANNs to run concurrently (line 6). This means that each n node ANN would be assigned to a specific thread run. This approach allowed one to learn the workload of each segment of the program code during different iterations of the program. It was obvious that assigning a different number of hidden nodes to an ANN required different efforts, i.e., for an ANN with small hidden layer nodes, one can accomplish the training and testing more quickly than for an ANN with a higher number of hidden

nodes. Since we assigned a dedicated thread to work on an ANN, this approach gave the situation of an unbalanced workload among various threads. This is because a thread working on an ANN with 1 hidden node, for example, will obviously finish faster than a thread working on an ANN with 9 hidden nodes. So even though there was some speedup with static scheduling, we felt that this could be improved.

In order to parallelize even further, consider line 7, which trains the network by going through one data item at a time. Each time, it goes through the forward phase, backward phase and then modifies the weights after finding the gradients using the gradient descent method. This is the so-called stochastic method (also known as online method or incremental method in various internet literatures). So instead of updating the weights one at a time, the weights can be modified as a collection, i.e., compute the weight changes (the gradients of weight change based on the error that was back propagated from the output layer) of all data items and keep these weight changes in a temporary data structure. After processing all data items, the weights can be updated in parallel by adding up all the weight changes for each item together. This method is usually known as *batch method*.

To further improve the performance, we changed the OpenMP scheduling type from static to dynamic and experimented with an increasing counter in the for loop (i.e. iterating from 0 to total_ann) and a decreasing counter in the for loop (iterating from total_ann to 0) and observed their effects on the execution time of the program. We found that for dynamic scheduling, using increasing or decreasing counters did not yield a significant difference in results. However, the results discussed in the next section show that that reorganizing the program code from static to dynamic did affect and improve the performance of the system.

4. EXPERIMENTAL RESULTS

In terms of the accuracy of results, we observed that the number of nodes that achieved the best hit ratio was five nodes in the hidden layer. The number of nodes that achieved the best MSE was having only one node in the hidden layer. However, we also observed that having four nodes in the hidden layer gave the second best hit ratio and second best MSE. After running the program multiple times, we concluded that it's not a simple task to find a universal "best" number of hidden nodes for accuracy that will be true for all stocks.

The following table shows the speedup of running the program using different number of threads. The time is the total number of seconds from beginning to end of running the whole program, including the testing phase. It includes the sequential portion and parallel portion of this program.

The table below, Figure 2, shows these speedup results when using dynamic scheduling of the program code. Although it is not linear, it does show some speed up.

number of threads	time	speedup
1	271.744	1
2	166.021	1.636805
4	105.95	2.564832
8	72.7911	3.733204

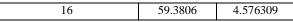


Figure 2

The corresponding efficiency of the results is drawn as the line chart in Figure 3. The results show that efficiency decreases when the number of threads are increased.

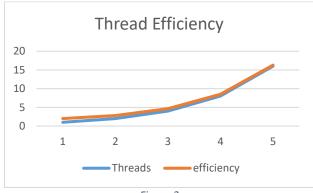


Figure 3

We also found that by changing the order of execution of the ANN, the results were affected. The following table, Figure 4, shows the speedup from running the program with static scheduling.

number of threads	speedup
1	1
2	1.353529353
4	2.746868554
8	4.459963154
16	4.086538969

Figure 4

In general, we see that there is less speedup when using static scheduling. This is most likely is due to the workload imbalance that occurs with static scheduling. This type of schedule will result in certain threads doing less work than other threads, as running the program with a lower number of hidden nodes will result in lesser work. It is also interesting to note that when using static scheduling, running with 8 threads gave a better speedup than 16 threads. We believe that this might have been the case because the overhead from thread creation far outweighed the benefits of using more threads.

5. CONCLUSIONS AND REMARKS

The financial industry is an industry that requires multiple disciplines to work together. Skills including coding, math, psychology, politics may be necessary to ensure its success.

In this project, we implemented a neural network that can predict the prices of stock, which then helps in determining volatility, using the feedforward and backward propagation method to change weights of a neural network. OpenMP was used to implement the parallel program. There was speedup observed, although not linear, and efficiencies were also computed. Static and dynamic scheduling methods of OpenMP were implemented and the results from these two schedules were compared.

It was found that increasing the number of hidden layer nodes did not imply better results. It would be interesting to further examine what happens when one adapts more layers in the computation. How many hidden nodes would be required in this case? And how would we decide the number of nodes in each hidden layer?

In addition, further work could be done to figure out what other factor(s) should be fed in into the system so that we would have a better hit ratio and accuracy, with regards to determining the volatility of stock.

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